

**Least Squares Estimator for Ornstein-Uhlenbeck  
Processes Driven by Stable Lévy Motions**

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## **Outline**

1. Formulation of LSE for Generalized O-U Processes
2. Strong Consistency of LSE
3. Asymptotic Distribution of LSE
4. Simulations

# 1. Formulation of LSE for Generalized O-U Processes

- Generalized Ornstein-Uhlenbeck processes  $\{X_t\}$ :

$$dX_t = -\theta_0 X_t dt + dZ_t, \quad X_0 = x. \quad (1)$$

on some probability space  $(\Omega, \mathcal{F}, P)$ , where  $\theta_0 > 0$  is an unknown parameter.

- $\{Z_t, t \geq 0\}$  is a standard symmetric  $\alpha$ -stable Lévy motion ( $\alpha \in (1, 2)$ ) so that  $Z_1$  has a symmetric  $\alpha$ -stable distribution  $S_\alpha(1, 0, 0)$  with c.f.

$$u \mapsto \exp(-|u|^\alpha).$$

- **Remark:** (1) In general, a random variable  $\eta$  is said to have a stable distribution with index of stability  $\alpha \in (0, 2]$ , scale parameter  $\sigma \in (0, \infty)$ , skewness parameter  $\beta \in [-1, 1]$ , and location parameter  $\mu \in (-\infty, \infty)$  if it has characteristic function of the following form:

$$\phi_\eta(u) = E \exp\{iu\eta\} = \begin{cases} \exp\{-\sigma^\alpha |u|^\alpha (1 - i\beta \operatorname{sgn}(u) \tan \frac{\alpha\pi}{2}) + i\mu u\}, & \text{if } \alpha \neq 1, \\ \exp\{-\sigma |u| (1 + i\beta \frac{2}{\pi} \operatorname{sgn}(u) \log |u|) + i\mu u\}, & \text{if } \alpha = 1. \end{cases}$$

We denote  $\eta \sim S_\alpha(\sigma, \beta, \mu)$ .

(2) Stable distributions are introduced by Paul Lévy (1925). Applications in modeling financial data: Mandelbrot (1963), Fama (1965), Officer (1972), Mittnik and Rachev (2001), Rachev (2003), Nolan (2005).

(3) Stable distributions are heavy-tailed and for  $\eta \sim S_\alpha(\sigma, \beta, \mu)$ ,  $E(|\eta|^q) = \infty$  ( $q \geq \alpha$ ).

(4) Brownian motion is almost surely continuous, while stable Lévy motion is a pure jump process (more appropriate to model extreme events).

- Discrete observations:  $(X_{t_i})_{i=0}^n$  with  $t_i = ih$ .
- Our goal: (i) Construct LSE of  $\theta_0$  based on discrete observations; (ii) Study the high frequency ( $h \rightarrow 0$ ) asymptotics of the LSE.
- Historical Comments:  
Least squares method is a classical method: parameter estimation in regression models, time series models, diffusion models, and jump-diffusion models. Several related references: Dorogovcev (1976), Le Breton (1976), Prakasa Rao (1983), Kasonga (1988), Masuda (2005), Shimizu (2006), Shimizu and Yoshida (2006).
- Our model is simple but can not be covered by those models mentioned above. This is due to the infinite variance property of  $\alpha$ -stable Levy motions.
- Our model has been used in physics, e.g., in geophysical turbulence and climate dynamical changes [see Ditlevsen (1999), Schertzer et al (2001)].

- The SDE (1) can be approximated by Euler scheme [see Jacod (2004), Jacod et al (2005)]

$$X_{t_i} = X_{t_{i-1}} - \theta X_{t_{i-1}} \Delta t_i + \Delta Z_{t_i},$$

where  $\Delta t_i = t_i - t_{i-1} = h$  and  $\Delta Z_{t_i} = Z_{t_i} - Z_{t_{i-1}}$ .

- We may regard  $X_{t_{i-1}} - \theta X_{t_{i-1}} \Delta t_i$  as a prediction of  $X_{t_i}$ .
- Contrast function:

$$\rho_n(\theta) = \sum_{i=1}^n |X_{t_i} - X_{t_{i-1}} + \theta X_{t_{i-1}} \cdot \Delta t_{i-1}|^2. \quad (2)$$

- LSE of  $\theta_0$ :

$$\hat{\theta}_n = - \frac{\sum_{i=1}^n (X_{t_i} - X_{t_{i-1}}) X_{t_{i-1}}}{h \sum_{i=1}^n X_{t_{i-1}}^2}. \quad (3)$$

- An equivalent expression:

$$\hat{\theta}_n = \frac{1 - e^{-\theta_0 h}}{h} - \frac{\sum_{i=1}^n X_{t_{i-1}} \cdot \int_{t_{i-1}}^{t_i} e^{-\theta_0(t_i-s)} dZ_s}{h \sum_{i=1}^n X_{t_{i-1}}^2}. \quad (4)$$

- Strong consistency and asymptotic distribution of  $\hat{\theta}_n$ .

## 2. Strong Consistency of the LSE

### 2.1. Stable stochastic integrals

- $L_{a.s.}^\alpha$  is the class of real-valued predictable processes  $F$  such that for every  $T > 0$ ,  $\int_0^T |F(t, \omega)|^\alpha dt < \infty$  a.s.
- First define stochastic integral w.r.t  $Z_t$  for simple predictable process and then for general predictable process in  $L_{a.s.}^\alpha$ :  
 $\int_0^t F(s) dZ_s$ . [see Rosinski and Woyczynski (1986), Kallenberg (1992)]
- **Random time change:**  
Let  $F \in L_{a.s.}^\alpha$  such that  $\tau(u) = \int_0^u |F|^\alpha dt \rightarrow \infty$  as  $u \rightarrow \infty$ .  
Then, there exists an independent process  $Z'$  (with same distribution as  $Z$ ) such that

$$\int_0^t F dZ = Z'(\tau(t)).$$

- **Limit Theorem:** Let  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  be increasing. If  $\tau(u) \rightarrow \infty$  a.s. as  $u \rightarrow \infty$ , then

$$\limsup_{t \rightarrow \infty} \left| \int_0^t F dZ \right| / \varphi(\tau(t)) = 0 \text{ or } = \infty \text{ a.s.}$$

according to

$$\int_1^\infty \varphi(t)^{-\alpha} dt < \infty \text{ or } = \infty.$$

## 2.2. Strong Consistency

- $X_t$  is ergodic ( $\theta_0 > 0$ ) and  $X_t \Rightarrow X_\infty$  as  $t \rightarrow \infty$ , where  $X_\infty = \int_0^\infty e^{-\theta_0 t} dZ_t$  [see Sato (1999)].
- **Theorem 1:** Assume that  $h \rightarrow 0$  and  $t_n = nh \rightarrow \infty$ . Then,

$$\hat{\theta}_n \rightarrow \theta_0 \text{ almost surely as } n \rightarrow \infty. \quad (5)$$

- **Proof ideas:**

- Let  $\phi_n(t) = \sum_{i=1}^n X_{t_{i-1}} e^{-\theta(t_i-t)} 1_{(t_{i-1}, t_i]}(t)$  and  $\tau_n(t_n) = \int_0^{t_n} |\phi_n(t)|^\alpha dt$ .
- Rewrite:

$$\hat{\theta}_n = \frac{1 - e^{-\theta_0 h}}{h} - \frac{\int_0^{t_n} \phi_n(t) dZ_t}{\tau_n(t_n)} \cdot \frac{\tau_n(t_n)}{h \sum_{i=1}^n X_{t_{i-1}}^2}. \quad (6)$$

- Ergodic theorem:

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n |X_{t_{i-1}}|^2 = E[X_\infty^2] = \infty \quad \text{a.s.}$$

- Ergodic theorem plus limit theorem imply the almost sure convergence.

### 3. Asymptotic Distribution of LSE

#### 3.1. Main Result

- **(A1):** As  $n \rightarrow \infty$ ,  $h \rightarrow 0$ ,  $nh^{1+\alpha}/\log n \rightarrow 0$ ,  $nh^{2\alpha-1} \log n \rightarrow \infty$ , and  $nh^{2-\alpha/2+\rho} \rightarrow \infty$  for some  $\rho > 0$ .
- Let  $C_\alpha = \left(\int_0^\infty x^{-\alpha} \sin(x) dx\right)^{-1} = [\Gamma(1-\alpha) \cos(\pi\alpha/2)]^{-1}$ ,  $\sigma_1 = C_{\alpha/2}^{-2/\alpha}$ , and  $\sigma_2 = C_\alpha^{-1/\alpha}$ .
- **Theorem 2:** Under the condition (A1), we have

$$\left(\frac{n}{\log n}\right)^{1/\alpha} h^{1/\alpha}(\hat{\theta}_n - \theta_0) \Rightarrow \frac{2\theta_0(\alpha\theta_0)^{-1/\alpha}\tilde{Y}}{Y_0}, \quad (7)$$

where  $Y_0$  and  $\tilde{Y}$  are independent stable random variables,  $Y_0$  is positive  $\alpha/2$ -stable with distribution  $S_{\alpha/2}(\sigma_1, 1, 0)$ ,  $\tilde{Y}$  is symmetric  $\alpha$ -stable with distribution  $S_\alpha(\sigma_2, 0, 0)$ .

- **Remark:** The rate of convergence  $\left(\frac{\log n}{nh}\right)^{1/\alpha}$  is considerably faster than the rate  $(nh)^{-1/2}$  in the classical Brownian motion case.



### 3.2. Some Preliminaries

- We have (denoting  $X_{t_i}$  by  $X_i$ )

$$\begin{aligned}
& \left( \frac{n}{\log n} \right)^{1/\alpha} h^{1/\alpha} (\hat{\theta}_n - \theta_0) \\
&= \left( \frac{n}{\log n} \right)^{1/\alpha} h^{1/\alpha} [h^{-1}(1 - e^{-\theta_0 h}) - \theta_0] \\
& \quad \frac{(n \log n)^{-1/\alpha} h^{-1/\alpha} \sum_{i=1}^n X_{i-1} \int_{t_{i-1}}^{t_i} e^{-\theta_0(t_i-s)} dZ_s}{n^{-2/\alpha} h^{1-\frac{2}{\alpha}} \sum_{i=1}^n X_{i-1}^2} \\
&:= \Lambda_n - \frac{\Phi_1(n)}{\Phi_2(n)}. \tag{8}
\end{aligned}$$

- Note that

$$X_i = e^{-\theta_0 i h} X_0 + \sum_{k=1}^i e^{-\theta_0 i h} \int_{t_{k-1}}^{t_k} e^{\theta_0 s} dZ_s. \tag{9}$$

- Let  $V_{k-1} = \int_{t_{k-1}}^{t_k} e^{\theta_0 s} dZ_s$ . and  $\tau_{k-1} = \int_{t_{k-1}}^{t_k} |e^{\theta_0 s}|^\alpha ds$ ,  
 $U_{k-1} = V_{k-1} / \tau_{k-1}^{\frac{1}{\alpha}}$ . By scaling property of stable distribution, we know that  $U_0, U_1, U_2, \dots$  are i.i.d. with the same distribution  $S_\alpha(1, 0, 0)$ .

- $X_i$  can be represented as

$$\begin{aligned} X_i &= e^{-\theta_0 i h} X_0 + \left( \frac{e^{\alpha \theta_0 h} - 1}{\alpha \theta_0} \right)^{1/\alpha} \sum_{k=1}^i e^{-\theta_0(i-k+1)h} U_{k-1} \\ &= c_{i,h} X_0 + \gamma_h \sum_{j=1}^i c_{j,h} U_{i-j}, \end{aligned} \quad (10)$$

where  $c_{i,h} = e^{-\theta_0 i h}$  and  $\gamma_h = \left( \frac{e^{\alpha \theta_0 h} - 1}{\alpha \theta_0} \right)^{1/\alpha}$ .

- **Remark:** For symmetric  $\alpha$ -stable random variable  $U_1 \sim S_\alpha(1, 0, 0)$ , we have

$$\lim_{x \rightarrow \infty} x^\alpha P(U_1 > x) = C_\alpha/2 \quad \text{and} \quad \lim_{x \rightarrow \infty} x^\alpha P(U_1 < -x) = C_\alpha/2.$$

- We introduce some scaling quantities:

$$\begin{aligned} a_n &= \inf \{ x : P(|U_1| > x) \leq n^{-1} \} \quad \text{and} \\ \tilde{a}_n &= \inf \{ x : P(|U_0 U_1| > x) \leq n^{-1} \}. \end{aligned}$$

- Thanks to the tail behavior, we may take

$$a_n = (C_\alpha n)^{\frac{1}{\alpha}} \quad \text{and} \quad \tilde{a}_n = C_\alpha^{\frac{2}{\alpha}} (n \log n)^{\frac{1}{\alpha}}.$$

- **Lemma 1** [Davis and Resnick (1986)]: Let  $\{U_i\}_{i=0}^\infty$  be i.i.d. with the same stable distribution  $S_\alpha(1, 0, 0)$ . Then, for  $a_n$  and  $\tilde{a}_n$  defined as above, we have for  $m \in \mathbb{N}$

$$\begin{aligned} & \left( a_n^{-2} \sum_{i=1}^n U_i^2, \tilde{a}_n^{-1} \sum_{i=1}^n U_i U_{i+1}, \dots, \tilde{a}_n^{-1} \sum_{i=1}^n U_i U_{i+m} \right) \\ \Rightarrow & (Y_0, Y_1, \dots, Y_m), \end{aligned} \tag{11}$$

where  $Y_0, Y_1, \dots, Y_m$  are independent stable random variables,  $Y_0$  is positive  $\alpha/2$ -stable with distribution  $S_{\alpha/2}(\sigma_1, 1, 0)$ ,  $Y_1, \dots, Y_m$  are i.i.d. symmetric  $\alpha$ -stable with distribution  $S_\alpha(\sigma_2, 0, 0)$ .

### 3.3. Proof Ideas for Theorem 2

- The asymptotic behavior of  $\left(\frac{n}{\log n}\right)^{1/\alpha} h^{1/\alpha}(\hat{\theta}_n - \theta_0)$  will be determined by the asymptotic behavior of  $\Lambda_n$ ,  $\Phi_1(n)$  and  $\Phi_2(n)$ .
- It is obvious that  $\Lambda_n \rightarrow 0$  as  $n \rightarrow \infty$  under condition (A1).
- **Proposition 1:** Under condition (A1), we have

$$\Phi_2(n) \Rightarrow \frac{C_\alpha^{2/\alpha} Y_0}{2\theta_0}, \quad (12)$$

where  $Y_0$  is a random variable with positively skewed stable distribution  $S_{\alpha/2}(\sigma_1, 1, 0)$  as specified in Theorem 2.

- Proof idea of Proposition 1:
  - Decomposition of  $\Phi_2(n)$ :

$$\begin{aligned} \Phi_2(n) &= n^{-2/\alpha} h^{1-2/\alpha} \sum_{i=1}^n X_{i-1}^2 \\ &= n^{-2/\alpha} h^{1-2/\alpha} X_0^2 + n^{-2/\alpha} h^{1-2/\alpha} \sum_{i=1}^{n-1} X_i^2 \\ &:= \Phi_{2,1}(n) + \Phi_{2,2}(n). \end{aligned} \quad (13)$$

and

$$\begin{aligned}
& \Phi_{2,2}(n) \\
&= n^{-2/\alpha} h^{1-2/\alpha} \sum_{i=1}^{n-1} \left[ c_{i,h} X_0 + \gamma_h \sum_{j=1}^i c_{j,h} U_{i-j} \right]^2 \\
&= n^{-2/\alpha} h^{1-2/\alpha} \sum_{i=1}^{n-1} c_{i,h}^2 X_0^2 \\
&\quad + 2n^{-2/\alpha} h^{1-2/\alpha} \gamma_h \sum_{i=1}^{n-1} c_{i,h} X_0 \sum_{j=1}^i c_{j,h} U_{i-j} \\
&\quad + n^{-2/\alpha} h^{1-2/\alpha} \gamma_h^2 \sum_{i=1}^{n-1} \sum_{j=1}^i c_{j,h}^2 U_{i-j}^2 \tag{14} \\
&\quad + n^{-2/\alpha} h^{1-2/\alpha} \gamma_h^2 \sum_{i=1}^{n-1} \sum_{j=1}^i \sum_{k=1, k \neq j}^i c_{j,h} c_{k,h} U_{i-j} U_{i-k}.
\end{aligned}$$

– By using some basic inequalities, truncation techniques, and Karamata's theorem, we can prove that

$$\Phi_2(n) - n^{-2/\alpha} h^{1-2/\alpha} \gamma_h^2 \sum_{i=1}^{n-1} \sum_{j=1}^i c_{j,h}^2 U_{i-j}^2 \xrightarrow{P} 0. \tag{15}$$

- By using some basic inequalities and Lemma 1, we can show that

$$n^{-2/\alpha} h^{(\alpha-2)/\alpha} \gamma_h^2 \sum_{i=1}^{n-1} \sum_{j=1}^i c_{j,h}^2 U_{i-j}^2 \Rightarrow \frac{C_\alpha^{2/\alpha} Y_0}{2\theta_0}, \quad (16)$$

where  $Y_0$  is a random variable with positively skewed stable distribution  $S_{\alpha/2}(\sigma_1, 1, 0)$  as specified in Theorem 2.

- **Proposition 2:** Under the condition (A1), we have

$$\Phi_1(n) \Rightarrow C_\alpha^{2/\alpha} Y \quad (17)$$

as  $n \rightarrow \infty$ , where  $Y$  is a random variable with stable distribution  $S_\alpha((\alpha\theta_0)^{-1/\alpha}\sigma_2, 0, 0)$ .

- Proof idea is similar to that of Proposition 1, i.e., using some decomposition technique, basic inequalities, Lemma 1 and Skorohod's representation theorem.
- Finally, the proof of **Theorem 2** is completed by combining Propositions 1 and 2.

## 4. Simulations

- We apply our estimator to the following stochastic differential equation:

$$dX_t = -\theta_0 X_t dt + dZ_t, \quad X_0 = 1,$$

where  $\theta_0 = 2$  and  $Z_t$  is a stable process with index  $\alpha = 1.8$ . We simulate the process on the interval  $[0, T]$  with  $T = 200$ .

- We plot  $\hat{\theta}_T = \hat{\theta}_n$  (where  $T = nh$ ) as a function of  $T$  for  $h = 0.05$  ( Figure 1) and  $h = 0.01$  ( Figure 2).
- The following table describes  $\theta(25), \dots, \theta(200)$  for different choice of  $h$ .

$T =$	25	50	75	100	125	150	175	200
$h = 0.1$	1.3304	1.4764	1.4409	1.4593	1.5903	1.6104	1.4234	1.3817
$h = 0.05$	1.7580	1.7326	1.7333	1.7051	1.4785	1.5509	1.5431	1.4053
$h=0.033$	2.3924	2.4681	2.4417	2.2373	2.2200	2.2094	2.1755	2.2002
$h=0.025$	1.8936	1.8320	1.8429	1.8323	1.8505	1.7615	1.7981	1.8109
$h=0.02$	2.0268	2.1199	2.1277	2.1162	2.1311	2.1529	2.1794	2.1734
$h=0.0167$	2.4107	2.5096	2.5188	2.4964	2.5093	2.5160	2.5260	2.5398
$h=0.0143$	2.2751	2.2514	2.1568	2.2191	2.0080	1.9516	1.6916	1.6516
$h=0.0125$	2.1116	1.9001	1.9310	1.9313	1.9313	1.9454	1.9353	1.9282

- We need to let both  $T$  goes to infinity and  $h$  goes to 0 to have the convergence of  $\hat{\theta}_T$  to  $\theta_0$ .

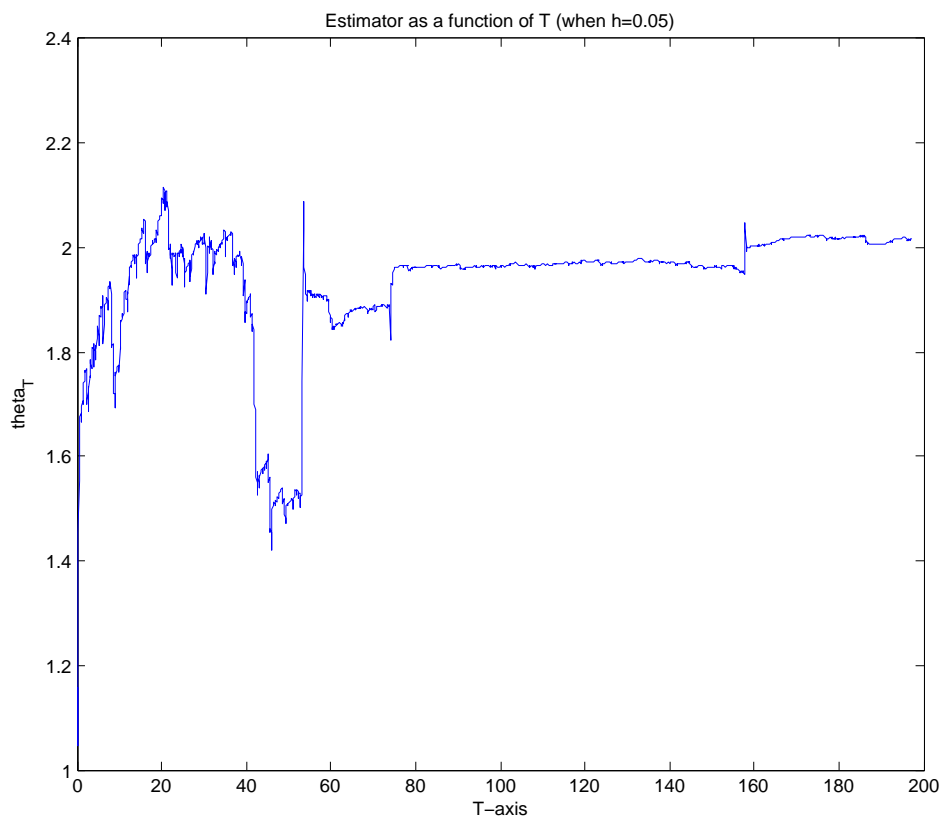


Figure 1: LSE for  $\theta_0 = 2$  when  $h = 0.05$



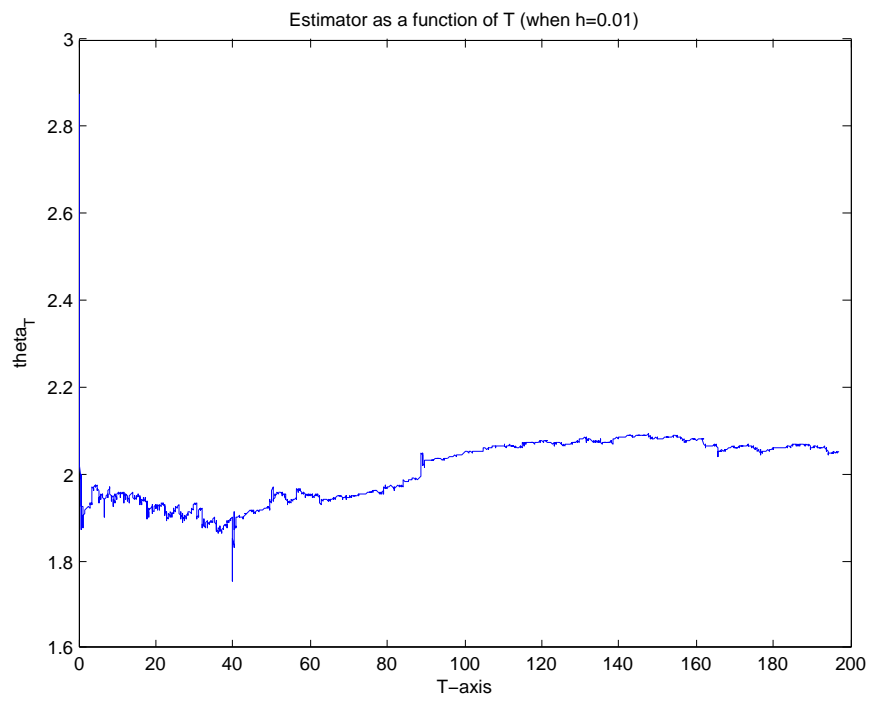


Figure 2: LSE for  $\theta_0 = 2$  when  $h = 0.01$