

FV scheme for conservation law:  $u_t + F_x = S$  (in 1D)

$x \in \Omega = (a, b), t > 0$

$u(x, t)$ : conserved quantity per unit volume at  $x$ , at time  $t$

$F(x, t)$ : flux of  $u$ : amount crossing a unit area per unit time

$S(x, t)$ : source of  $u$ : amount generated (or lost) per unit volume per unit time

... will derive this later...

Discretize space  $[a, b]$  into  $M$  control volumes  $V_i, i=1:M$

» time  $[0, t_{end}]$  into  $N_{max}$  timesteps  $t_n, n=0:N_{max}$

integrating the PDE over each  $V_i$  and over  $[t_n, t_{n+1}]$  ... details later...

explicit FV scheme: 
$$U_i^{n+1} = U_i^n + \frac{\Delta t}{\Delta x_i} [F_{i-\frac{1}{2}}^n - F_{i+\frac{1}{2}}^n] + \Delta t S_i^n$$
  

$$i=1:M, n=0, 1, 2, \dots, N_{max}$$

where

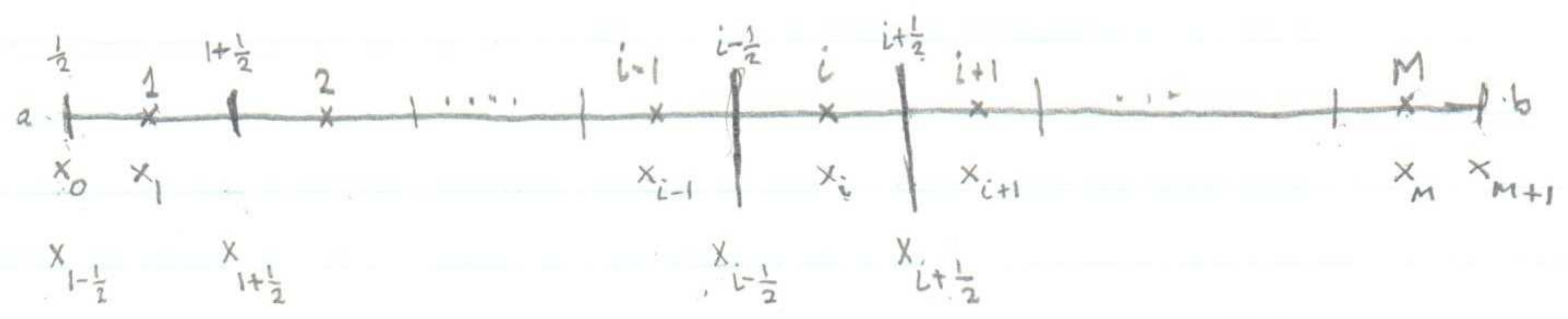
$$U_i^n = \text{mean value of } u \text{ over } V_i \text{ at time } t_n = \frac{1}{V_i} \int_{V_i} u(x, t_n) dx \approx u(x_i, t_n)$$

$$F_{i-\frac{1}{2}}^n = \text{mean flux during } [t_n, t_{n+1}] \text{ across face } x_{i-\frac{1}{2}} = \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} F(x_{i-\frac{1}{2}}, t) dt$$

$$S_i^n = \text{mean source over } V_i \text{ and timestep} = \frac{1}{\Delta t} \frac{1}{V_i} \int_{t_n}^{t_{n+1}} \int_{V_i} S(x, t) dx dt$$

$$\Delta x_i = x_{i+\frac{1}{2}} - x_{i-\frac{1}{2}} = \text{volume of } V_i = [x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}]$$

$$\Delta t = t_{n+1} - t_n = \text{timestep}$$

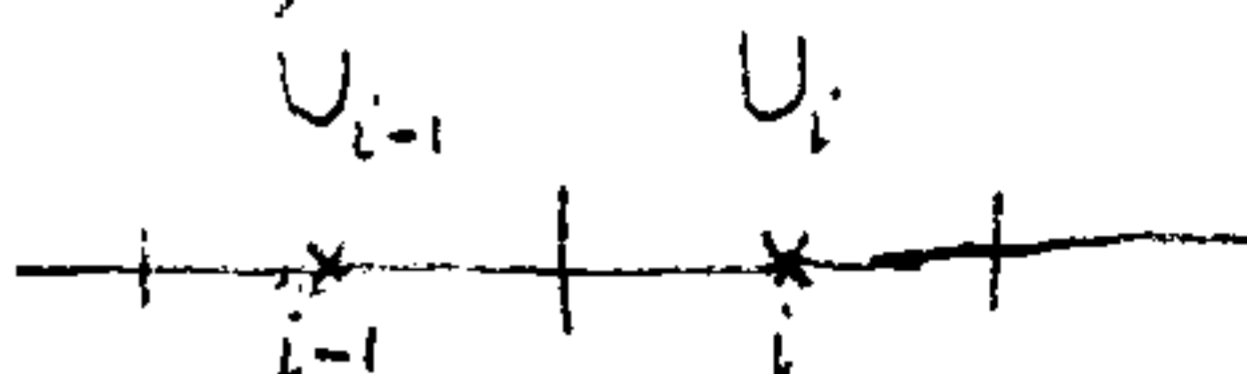


arrays:  $x(0:M+1), U(0:M+1), F(1:M+1)$  no time-index

# Explicit scheme - CFL condition for diffusion

Diffusion:  $F = -D u_x$  (Fick's Law, Fourier Law)

Approximation:  $F \approx F_{i-\frac{1}{2}} = -D_{i-\frac{1}{2}} \frac{U_i - U_{i-1}}{x_i - x_{i-1}}$



$= -D \frac{U_i - U_{i-1}}{\Delta x}$  for uniform mesh, const. D  
 $i=2:M$  (internal fluxes)

This is a major approximation, for expediency, simplicity:

we interpret mean values  $U_i$  as nodal values (at  $x_i$ )

Explicit FV scheme for  $u_t + F_x = 0$ :

$$U_i^{n+1} = U_i^n + \frac{\Delta t}{\Delta x} [F_{i-\frac{1}{2}}^n - F_{i+\frac{1}{2}}^n] \quad \begin{matrix} i=1:M \\ n=1:N_{max} \end{matrix}$$

This is the simplest, most physical, and most accurate <sup>1<sup>st</sup> order in time</sup> <sub>2<sup>nd</sup> order in space</sub>  
 (discretization error =  $O(\Delta t + \Delta x^2)$ )

The penalty for such simplicity is that we must restrict  $\Delta t$  for stability.

Stability condition: plug in  $F_{i-\frac{1}{2}}$  to get updating formula for  $U_i$ :

$$U_i^{n+1} = U_i^n + \frac{D \Delta t}{\Delta x^2} [U_{i-1}^n - 2U_i^n + U_{i+1}^n]$$

centered finite difference  $\approx u_{xx}$ , 2<sup>nd</sup> order in  $\Delta x$

$$\Rightarrow U_i^{n+1} = [1 - 2\mu] U_i^n + \mu [U_{i-1}^n + U_{i+1}^n]$$

Set  $\mu = \frac{D \Delta t}{\Delta x^2}$  = CFL number, dimensionless (Courant-Friedrichs-Lewy)   
 $\sim 1927?$

$$\Rightarrow U_i^{n+1} = (1 - 2\mu) U_i^n + \mu U_{i-1}^n + \mu U_{i+1}^n$$

Choose  $\Delta x, \Delta t$  so that, say,  $\mu = 5$ :  $U_i^{n+1} = -9U_i + 5U_{i-1} + 5U_{i+1}$

	$i=0$	$i=1$	$i=2$	$i=3$	$i=4$
$n=0$	0	1	2	1	0
$n=1$	0	$-9+5 \cdot 2 = +1$	$-9 \cdot 2 + 5 \cdot 2 = -8$	$-9+10 = +1$	0
$n=2$	0	$-9-40 = -49$	$+72+10 = +82$	$= -49$	0
$n=3$	0	+851	-1220	+851	0

Clearly nonsense! why?

## CFL condition

Trouble arose

because  $1 - 2\mu < 0$  can produce negative values from positive ones,  
so can produce smaller (and larger) values than bry or initial values.

This violates the Maximum Principle, a fundamental property of heat eqn:

The smallest and largest values of  $u(x,t)$   
must occur on the boundary or earlier (initially)

To prevent it, should respect the

Positive Coefficient Rule: in the update formula  $U_i^{n+1} = \dots$   
all coefficients must be ~~positive~~ <sup>non-negative</sup>.

So, we must demand  $1 - 2\mu \geq 0$  i.e.  $\mu \leq \frac{1}{2}$ , this is the famous

Courant-Friedrichs-Lewy (CFL) condition:  $0 < \mu = \frac{D \Delta t}{\Delta x^2} \leq \frac{1}{2}$

so must restrict the timestep:  $\Delta t \leq \frac{\Delta x^2}{2D} =: \Delta t_{\text{expl}}$

For safety against roundoff:  $\Delta t \leq \Delta t_{\text{expl}}$

or, better, choose  $\Delta t = \text{factor} \cdot \Delta t_{\text{expl}}$  and play with factor

0.99 or 0.95 or 0.90 ...

or 1 or 1.01 or 1.1 ...

## Code skeleton

- Inputs to be read from a "dat" file:  $MM, tend, dtout, factor, D, a, b$  |  $MM = \#$  of nodes per unit length  
 $dtout =$  how often to print output
- Set grid  
 $Dx = 1.0/MM, M = (b - a) * MM$   
`CALL MESH(M, a, b, Dx, x)` returns x array
- Set timestep (for stability of explicit scheme)  
 $Dt_{EXPL} = Dx * Dx / (2 * D)$   
 $Dt = factor * Dt_{EXPL}$   
 $Nmax = \text{int}(tend / Dt) + 1$   
`CALL INIT(...); CALL OUTPUT(...)` profile at  $t = 0$
- Initialize  
 $nsteps = 0$   
 $time = 0.0$   
 $tout = \text{MAX}(dtout, Dt)$
- Execute timestepping  
for  $nsteps = 1 : Nmax$   
`CALL FLUX(...)` returns F array  
`CALL PDE(...)` returns U array  
 $time = (time + Dt) = nsteps * Dt$   
if ( $time \geq tout$ )  
    `CALL OUTPUT(M, x, U, time, nsteps)`  
     $tout = tout + dtout$   
endif  
endfor
- Finish  
print: 'DONE, at time = ', time, ' after nsteps = ', nsteps  
END