

## Math 577 HW1 Spring 2018 solutions

#1)

$$(a) f(a+h) = b_0 + b_1 h + |h| \varepsilon(h) \quad (*)$$

$$h \rightarrow 0 \Rightarrow f(a) = b_0, \Rightarrow \frac{|f(a+h) - f(a) - b_1 h|}{|h|} = \varepsilon(h) \rightarrow 0$$

we know  $f'(a)$  exists and is unique. Hence  $b_1 = f'(a)$ .

(b) Again, let  $h \rightarrow 0 \Rightarrow f(a) = b_0$ .

$$(*) \Rightarrow \frac{|f(a+h) - f(a) - b_1 h|}{|h|} = \varepsilon(h) \rightarrow 0$$

hence by defn. of derivative  $f'(a)$  exists and  $f'(a) = b_1$ .

#2)(a)

$$(*) f(a+h) = b_0 + b_1 h + b_2 h^2 + |h|^2 \varepsilon(h), \quad \varepsilon(h) \rightarrow 0$$

$f$  twice diffble. at  $a \Rightarrow$  by Taylor

$$f(a+h) = f(a) + f'(a)h + \frac{1}{2}f''(a)h^2 + |h|^2 \tilde{\varepsilon}(h), \quad \tilde{\varepsilon}(h) \rightarrow 0$$

Subtracting this from  $(*)$

$$0 = (b_0 - f(a)) + (b_1 - f'(a))h + (b_2 - \frac{1}{2}f''(a))h^2 + |h|^2(\varepsilon(h) - \tilde{\varepsilon}(h)).$$

Again, taking  $h \rightarrow 0$ , we successively get

$$b_0 = f(a), \quad b_1 = f'(a), \quad b_2 = \frac{1}{2}f''(a).$$

(b) let  $f(x) = x^3 \sin \frac{1}{x}$ ,  $x \neq 0$  and  $f(0) = 0$ .

$$\text{we have } f(0+h) = 0 + 0 \cdot h + 0 \cdot h^2 + h^2 \underbrace{h \sin \frac{1}{h}}_{\varepsilon(h)}, \quad \varepsilon(h) = h \sin \frac{1}{h} \rightarrow 0.$$

$$\text{On the other hand } f'(x) = 3x^2 \sin \frac{1}{x} - x \cos \frac{1}{x}, \quad x \neq 0$$

$$= 0 \quad x = 0$$

but  $f'$  is not diffble. at 0.

$$\#13) \quad h = (h_1, h_2), \quad \frac{1}{t} [f(0+t(h_1, h_2)) - f(0)] \quad t \neq 0, (h_1, h_2) \neq (0, 0)$$

$$= \frac{t^5 h_1^5}{t[(th_2 - th_1^2)^2 + t^8 h_1^8]} = \frac{t^2 h_1^5}{(h_2 - th_1^2)^2 + t^5 h_1^8}$$

If  $h_1 = 0$ , Then  $h_2 \neq 0 \Rightarrow \lim_{t \rightarrow 0} = 0$

If  $h_1 \neq 0$  and  $h_2 \neq 0$ , Then  $\lim_{t \rightarrow 0} = 0$

If  $h_1 \neq 0$  and  $h_2 = 0$ , Then  $\lim_{t \rightarrow 0} \frac{t^2 h_1^5}{t^2 h_1^4 + t^5 h_1^8} = \lim_{t \rightarrow 0} \frac{h_1^5}{h_1^4 + t^3 h_1^8} = h_1$

Hence in all cases the limit exists  $\Rightarrow f$  is G-diffble. at  $(0, 0)$ .

To show  $f$  is not continuous at  $(0, 0)$ , take limit of  $f$  along the path  $y = x^2$ .  $x \neq 0$

$$\Rightarrow f(x, x^2) = \frac{x^5}{x^8} \text{ . Thus } \lim_{\substack{y=x^2 \\ x \rightarrow 0}} f(x, y) \text{ does not exist.}$$

Hence  $f$  is not continuous at  $(0, 0)$ .

$$\#4) \quad \lim_{t \rightarrow 0} \frac{\|0 + th\| - \|0\|}{t} = \lim_{t \rightarrow 0} \frac{|t| \|h\|}{t} = \begin{cases} \|h\| & \text{if } t \rightarrow 0^+ \\ -\|h\| & \text{if } t \rightarrow 0^- \end{cases}$$

#5) we will use the following result: /

$A$  invertible and  $\|A^{-1}E\| < 1 \Rightarrow A-E$  invertible

write  $B = A - E$ ,  $E = A - B$ . Then

$$\|A^{-1}E\| = \|A^{-1}(A-B)\| \leq \|A^{-1}\| \|A-B\| \leq \|A^{-1}\| \delta.$$

Hence for  $\delta < \frac{1}{\|A^{-1}\|}$  we will have  $\|A^{-1}E\| < 1$ .

#6/  $U^T A V = \Sigma \iff A = U \Sigma V^T$ .

of course if  $A$  is singular,  $\inf_{B \in S} \|A - B\|_2 = 0 = \sigma_n(A)$ .  
 So suppose  $A$  is invertible.

Claim  $\|A - B\|_2 \geq \sigma_n$  for any  $B \in S$ .

$\exists \hat{x}, \|\hat{x}\|_2 = 1$  such that  $B\hat{x} = 0$

$\|A - B\|_2 = \sup_{\|x\|_2=1} \|(A - B)x\|_2 \geq \|(A - B)\hat{x}\|_2 = \|A\hat{x}\|_2$

$\|A\hat{x}\|_2^2 = \|U \Sigma V^T \hat{x}\|_2^2 = \|\Sigma V^T \hat{x}\|_2^2$ ,  $U$  orthogonal = isometry

let  $\hat{z} = V^T \hat{x} \implies \|A\hat{x}\|_2^2 = \|\Sigma \hat{z}\|_2^2 = \sum_{i=1}^n \sigma_i^2 \hat{z}_i^2 \geq \sigma_n^2 \|\hat{z}\|_2^2$

$\implies \|A\hat{x}\|_2^2 \geq \sigma_n^2 \|\hat{z}\|_2^2 = \sigma_n^2 \|V^T \hat{x}\|_2^2 = \sigma_n^2 \|\hat{x}\|_2^2 = \sigma_n^2 \checkmark$

Finally, let  $B = U \begin{bmatrix} \sigma_1 & & 0 \\ & \ddots & \\ 0 & & \sigma_n \\ & & & 0 \end{bmatrix} V^T$ ,  $B$  is singular

$\|A - B\|_2 = \|U \begin{bmatrix} 0 & & 0 \\ & \ddots & \\ 0 & & \sigma_n \\ & & & 0 \end{bmatrix} V^T\|_2 = \sigma_n$ ,  $U, V$  orthogonal.  $\checkmark$

#7) If  $A$  is invertible, take  $A_\epsilon = A \checkmark$

let  $A = U \Sigma V^T$ . let  $A_\epsilon = U(\Sigma + \delta I)V^T$  ( $\delta$  to be chosen later)

Since the singular values  $\sigma_1, \dots, \sigma_n$  form a finite set, there exists  $c > 0$  such that  $\sigma_i + \delta \neq 0, i=1, \dots, n, \forall \delta$  with  $|\delta| < c$

$\implies \|A - A_\epsilon\| = \|U(-\delta I)V^T\| \leq |\delta| \|U\| \|V^T\|$

Now choose  $|\delta| < \min\{c, \frac{\epsilon}{\|U\| \|V^T\|}\}$ .  $\checkmark$

Alternatively, take  $A_\epsilon = A - \epsilon I$  for  $\epsilon$  small,  $A_\epsilon$  is invertible since eigenvalues of  $A_\epsilon$  are  $\lambda - \epsilon$ , a eig. of  $A$ .

$\|A - A_\epsilon\| = |\epsilon| \|I\|$



#8/ (i)  $\langle x, x \rangle_A = x^T A x > 0 \quad \forall x \neq 0$  since  $A$  is s.p.d.

(ii)  $\langle x, y \rangle_A = x^T A y = (x^T A y)^T = y^T A^T x = y^T A x = \langle y, x \rangle_A$

(iii) clearly  $\langle x, y \rangle_A$  is bilinear !!

#9/  $\langle x, B A y \rangle_A = x^T A B A y = y^T A^T B^T A^T x = y^T A B A x$

$= \langle y, B A x \rangle_A = \langle B A x, y \rangle_A$  by (ii) in #8

$\langle x, B A y \rangle_{B^{-1}} = x^T B^{-1} B A y = x^T A y = y^T A^T x = y^T A x$

$= y^T B^{-1} B A x = \langle y, B A x \rangle_{B^{-1}} = \langle B A x, y \rangle_{B^{-1}} \checkmark$

#10/

$f(x+t h) - f(x) = (x+t h)^T A (x+t h) - b^T (x+t h) + c$

$= x^T A x + b^T x - c$

$+ t h^T A x + t x^T A h + t^2 h^T A h - t b^T h$

Hence

$\lim_{t \rightarrow 0} \frac{1}{t} [f(x+t h) - f(x)] = h^T A x + x^T A h - b^T h = (A + A^T)x - b$

$\Rightarrow f'(x)h = (x^T A^T + x^T A - b^T)h \Rightarrow f'(x) = (A + A^T)x - b$

$f''(x)(h, k) = \lim_{t \rightarrow 0} \frac{1}{t} [f'(x+t k)h - f'(x)h] = h^T (A + A^T)k$

$\Rightarrow f''(x) = A + A^T$

#11/

$f(A+t H) - f(A) = (A+t H)^2 - A^2 = A^2 + t A H + t H A + t^2 H^2 - A^2$

$= t(A H + H A) + t^2 H^2$

Hence

$f'(A)H = A H + H A$

#12] For  $t$  small,  $I + tA^{-1}H$  is invertible and

$$\boxed{(I + tA^{-1}H)^{-1} = I - tA^{-1}H + o(t^2)} \quad (*)$$

$$\begin{aligned} \Rightarrow (A + tH)^{-1} - A^{-1} &= (A(I + tA^{-1}H))^{-1} - A^{-1} \\ &= (I + tA^{-1}H)^{-1}A^{-1} - A^{-1} \\ &= A^{-1} - tA^{-1}HA^{-1} + o(t^2) - A^{-1} \\ &= -tA^{-1}HA^{-1} + o(t^2). \end{aligned}$$

Hence

$$\lim_{t \rightarrow 0} \frac{1}{t} [(A + tH)^{-1} - A^{-1}] = -A^{-1}HA^{-1} = f'(A)H$$

The same argument works without  $t$ , i.e. for  $\|H\|$  small  $(A + H)^{-1}$  exists.

$$\begin{aligned} f''(A)(H, K) &= \lim_{t \rightarrow 0} \frac{1}{t} [-(A + tK)^{-1}H(A + tK)^{-1} + A^{-1}HA^{-1}] \\ &= \lim_{t \rightarrow 0} \frac{1}{t} [-[I - tA^{-1}K + o(t^2)]A^{-1}H[I - tA^{-1}K + o(t^2)] + A^{-1}HA^{-1}] \\ &= \lim_{t \rightarrow 0} \frac{1}{t} [-A^{-1}HA^{-1} + tA^{-1}KA^{-1}HA^{-1} + tA^{-1}HA^{-1}KA^{-1} + o(t^2) + A^{-1}HA^{-1}] \\ &= A^{-1}KA^{-1}HA^{-1} + A^{-1}HA^{-1}KA^{-1}. \quad \checkmark \end{aligned}$$

#13] Let  $f: V^n \rightarrow Y$  be an  $n$ -linear map. Then

$$f(v_1 + tw_1, v_2 + tw_2, \dots, v_n + tw_n) = f(v_1, \dots, v_n)$$

$$+ t \{ f(w_1, v_2, \dots, v_n) + f(v_1, w_2, v_3, \dots, v_n) + \dots + f(v_1, \dots, v_{n-1}, w_n) \} + o(t^2)$$

If  $a_1, \dots, a_n$  and  $h_1, \dots, h_n$  denote the columns of  $A$  and  $H$  respectively

$$\det(A + tH) = \det(A) + t \{ \det(h_1, a_2, \dots, a_n) + \dots + \det(a_1, \dots, a_{n-1}, h_n) \} + o(t^2)$$



Hence 
$$\lim_{t \rightarrow 0} \frac{1}{t} [\det(A+tH) - \det(A)]$$

$$= \det(h_{11}, a_{12}, \dots, a_{1n}) + \dots + \det(a_{11}, \dots, a_{n-1}, h_{nn}) = S$$

This is the sum of  $n$  determinants where by each column of  $A$  is replaced by a column of  $H$ .

Now 
$$\det(a_{11}, \dots, a_{k-1}, h_k, a_{k+1}, \dots, a_{nn}) = \sum_{i=1}^n h_{ki} C_{ki}$$

where  $\{C_{ki}\}$  are cofactors of  $A$ . Hence

$$S = \sum_{k=1}^n \sum_{i=1}^n h_{ki} C_{ki} = \sum_{k=1}^n \sum_{i=1}^n h_{ki} (\text{adj}(A))_{ik}$$

( $\text{adj}(A)$  is the transpose of the matrix of cofactors)

$$S = \sum_{i=1}^n \sum_{k=1}^n (\text{adj}(A))_{ik} h_{ki} = \sum_{i=1}^n (\text{adj}(A)H)_{ii}$$

$$= \text{tr}(\text{adj}(A)H).$$

#14)  $f(x) = \ln \det(x^{-1}) = \ln \left( \frac{1}{\det(x)} \right) = -\ln(\det(x))$

Now  $f = \phi \circ \psi$  where  $\psi: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$   $\psi(x) = \det(x)$   
 $\phi: \mathbb{R} \rightarrow \mathbb{R}$   $\phi(t) = \ln t$

By the chain rule

$$f'(x) = \phi'(\psi(x)) \psi'(x) \quad \phi'(t) = \frac{1}{t}$$

$$\psi'(x)H = \text{tr}(\text{adj}(x)H)$$

$$\Rightarrow f'(x)H = -\frac{1}{\psi(x)} \text{tr}(\text{adj}(x)H)$$

$$= -\frac{\text{tr}(\text{adj}(x)H)}{\det(x)} = \boxed{-\text{tr}(x^{-1}H)}$$

using  $\text{adj}(x) \cdot x = \det(x) \cdot I \Rightarrow x^{-1} = \frac{\text{adj}(x)}{\det(x)}$

Note  $\text{tr}(AB) = \text{tr}(BA) \Rightarrow f'(x)H = -\text{tr}(HX^{-1})$

#15)  $f(x, y, z) = \sin(xyz) - z \quad f: \mathbb{R}^3 \rightarrow \mathbb{R}$

$\mathbb{R}^3 = \mathbb{R}^2 \times \mathbb{R}$ . So we can hope to solve for one variable in terms of the other two

$$\frac{\partial f}{\partial x} = yz \cos(xyz) \Big|_{\left(\frac{\pi}{2}, 1, 1\right)} = 0$$

So we cannot solve for  $x$  in terms of  $y, z$  in a nbhd. of the point  $\left(\frac{\pi}{2}, 1, 1\right)$

$$\frac{\partial f}{\partial y} = xz \cos(xyz) \Big|_{\left(\frac{\pi}{2}, 1, 1\right)} = 0 \quad \text{Same for } y.$$

$$\frac{\partial f}{\partial z} = xy \cos(xyz) - 1 \Big|_{\left(\frac{\pi}{2}, 1, 1\right)} = -1, \text{ so } \exists \text{ a nbhd.}$$

$O_1$  of  $\left(\frac{\pi}{2}, 1\right)$  and a nbhd.  $I \in O_2$  such that

$$z = g(x, y) \quad z \in O_2, (x, y) \in O_1.$$

$$g' \left( \frac{\pi}{2}, 1 \right) = \begin{bmatrix} \frac{\partial z}{\partial x} \\ \frac{\partial z}{\partial y} \end{bmatrix} = -(-1)^{-1} \begin{bmatrix} yz \cos(xyz) \\ xz \cos(xyz) \end{bmatrix} \Big|_{\left(\frac{\pi}{2}, 1\right)} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

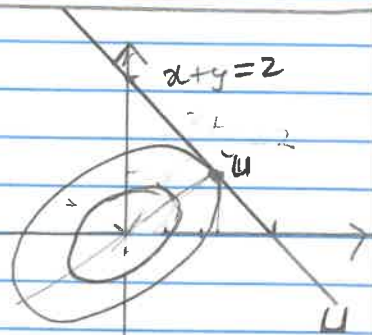
#16)  $f'(u) + \lambda \phi'(u) = (4x + 2y, 2x + 6y)$

$$+ \lambda(1, 1) = (0, 0)$$

$$\left. \begin{array}{l} 4x + 2y + \lambda = 0 \\ 2x + 6y + \lambda = 0 \end{array} \right\} \Rightarrow 4x + 2y = 2x + 6y$$

$$\Rightarrow 2x = 4y \Rightarrow x = 2y$$

$$x + y = 2 \Rightarrow 3y = 2 \Rightarrow \boxed{x = \frac{4}{3}} \quad \boxed{y = \frac{2}{3}}$$



The level curves of  $f$  are ellipses as shown centered at 0. So the point  $u = \left(\frac{4}{3}, \frac{2}{3}\right)$  corresponds to a local and global minimum of  $f$  with respect to  $L$ .

Also note the following:  $L$  is a subspace of  $\mathbb{R}^2$  and thus convex.



Furthermore  $f(x,y) = (x,y) \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$ .

A is s.p.d. hence  $f$  is strictly convex on  $\mathbb{R}^2$ . Also

$$f'(4/3, 2/3) = \frac{20}{3} \langle 1, 1 \rangle \text{ and is orthogonal to } W_u$$

$f'(u)(v-u) = 0 \quad \forall v \in U$

By part 3 of Thm 7.4-4,  $f$  has a local and global minimum at  $u = (4/3, 2/3)$ .

#17)  $f(x,y,z) = (x-3)^2 + (y-2)^2 + z^2$

$$\phi_1(x,y,z) = x^2 + y^2 - 1, \quad \phi_2(x,y,z) = y + z - 1$$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}, \quad f'(x,y,z) = \langle 2(x-3), 2(y-2), 2z \rangle$$

$$\phi'(x,y,z) = \begin{bmatrix} 2x & 2y & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

Note rows of  $\phi'$  are linearly independent. Hence by the Lo-Mo Theorem,  $\exists \lambda_1, \lambda_2$  such that

$$\langle 3x-6, 2y-4, 2z \rangle + (\lambda_1, \lambda_2) \begin{bmatrix} 2x & 2y & 0 \\ 0 & 1 & 1 \end{bmatrix} = \langle 0, 0, 0 \rangle.$$

These are 3 equations, combining them with the constraints, we get the system

$$\begin{cases} 3x - 6 + 2x\lambda_1 = 0 \\ 2y - 4 + 2y\lambda_1 + \lambda_2 = 0 \\ 2z + \lambda_2 = 0 \\ x^2 + y^2 - 1 = 0 \\ y + z - 1 = 0 \end{cases}$$

We can try to find solutions of this system using Newton's or some other method. However

- (1) there may be problems with convergence.
- (2) How do we know we found all solutions
- (3) Once a solution is found, how do we know if it corresponds to a local/global minimum or maximum, or neither.



As an alternative, we can try to find the restriction of  $f$  to  $U$ . In this case it is convenient to use parametric representations of  $\phi_1=0$  and  $\phi_2=0$

$$\begin{aligned}\phi_1 &\leftrightarrow \langle \cos t, \sin t, s \rangle & t, s \in \mathbb{R} \\ \phi_2 &\leftrightarrow \langle \tau, \sigma, 1-\sigma \rangle & \tau, \sigma \in \mathbb{R}\end{aligned}$$

Hence  $U \leftrightarrow \langle \cos t, \sin t, 1-\sin t \rangle \quad 0 \leq t \leq 2\pi$ .

Thus

$$\begin{aligned}g(t) = f|_U &= (\cos t - 3)^2 + (\sin t - 2)^2 + (1 - \sin t)^2 \\ &= 15 - 6\cos t - 6\sin t + \sin^2 t\end{aligned}$$

To find the extrema of  $g$  we use Newton's method on  $g'(t)$ . We find:

Local and global minimum at

$$\langle x, y, z \rangle = \langle 0.783575, 0.621297, 0.378703 \rangle$$

$$\text{with } f = 6.956777$$

Local and global maximum at

$$\langle x, y, z \rangle = \langle -0.621297, -0.783575, 1.783575 \rangle$$

$$\text{with } f = 24.043223$$

#18

$$f'(x, y, z) = \langle y, x+z, y \rangle$$

$$\phi_1'(x, y, z) = \langle y, x, 0 \rangle, \quad \phi_2'(x, y, z) = \langle 0, 2y, 2z \rangle$$

$$(y, x+z, y) + (\lambda_1, \lambda_2) \begin{bmatrix} y & x & 0 \\ 0 & 2y & 2z \end{bmatrix} = (0, 0, 0)$$

$$\begin{cases} y + \lambda_1 y = 0 \\ x + z + \lambda_1 x + 2\lambda_2 y = 0 \\ y + 2\lambda_2 z = 0 \\ xy - 1 = 0 \Rightarrow \boxed{x \neq 0, y \neq 0} \\ y^2 + z^2 = 1 = 0 \end{cases} \Rightarrow \begin{matrix} x, y \text{ have the same sign.} \end{matrix}$$

$$0 = y + \lambda_1 y = y(1 + \lambda_1) \Rightarrow \boxed{\lambda_1 = -1} \text{ since } y \neq 0.$$

$$\begin{matrix} \text{2nd eqn. } \lambda_1 = -1 \Rightarrow z + 2\lambda_2 y = 0 \Rightarrow z^2 + 2\lambda_2 y z = 0 \\ \text{3rd eqn. } \Rightarrow y + 2\lambda_2 z = 0 \Rightarrow y^2 + 2\lambda_2 y z = 0 \end{matrix} \Rightarrow \boxed{z^2 = y^2}$$

$$z^2 = y^2 \text{ and } y^2 + z^2 = 1 = 0 \Rightarrow \boxed{y = \pm \frac{1}{\sqrt{2}}, z = \pm \frac{1}{\sqrt{2}}}$$

We have 4 extrema

$$\left(\frac{\sqrt{2}}{2}, \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right) \text{ and } \left(-\frac{\sqrt{2}}{2}, -\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right) \text{ local/global min}$$

$$f = 1 - \frac{1}{2} - \frac{1}{2}$$

$$\left(\frac{\sqrt{2}}{2}, \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right) \text{ and } \left(-\frac{\sqrt{2}}{2}, -\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right) \text{ local/global max}$$

$$f = 1 + \frac{1}{2} = \frac{3}{2}$$

$$U \leftrightarrow \left\langle \frac{1}{\cos t}, \cos t, \sin t \right\rangle \quad 0 \leq t < 2\pi$$

$$\Rightarrow f|_U = 1 + \cos t \sin t$$

