

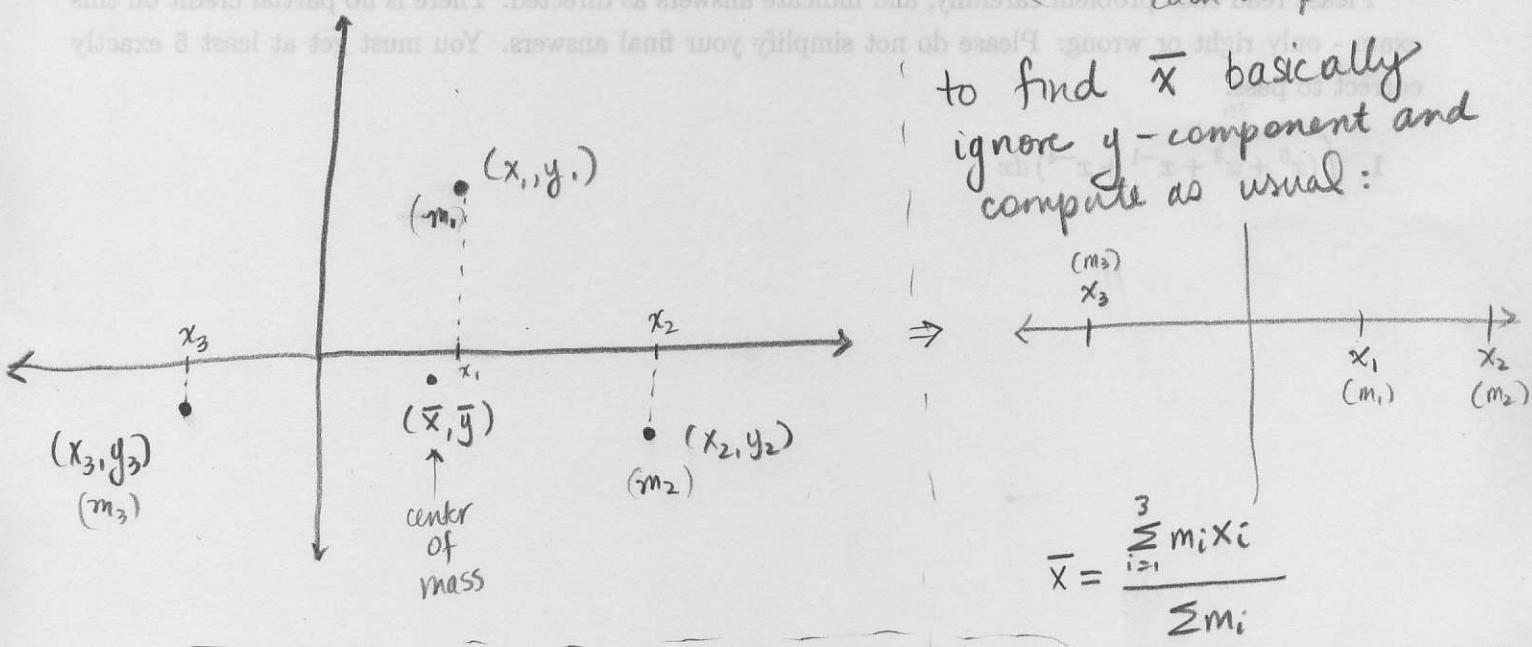
## Center of Mass in two dimensions:

Dependent on Multidimensional  
The Ohio State University

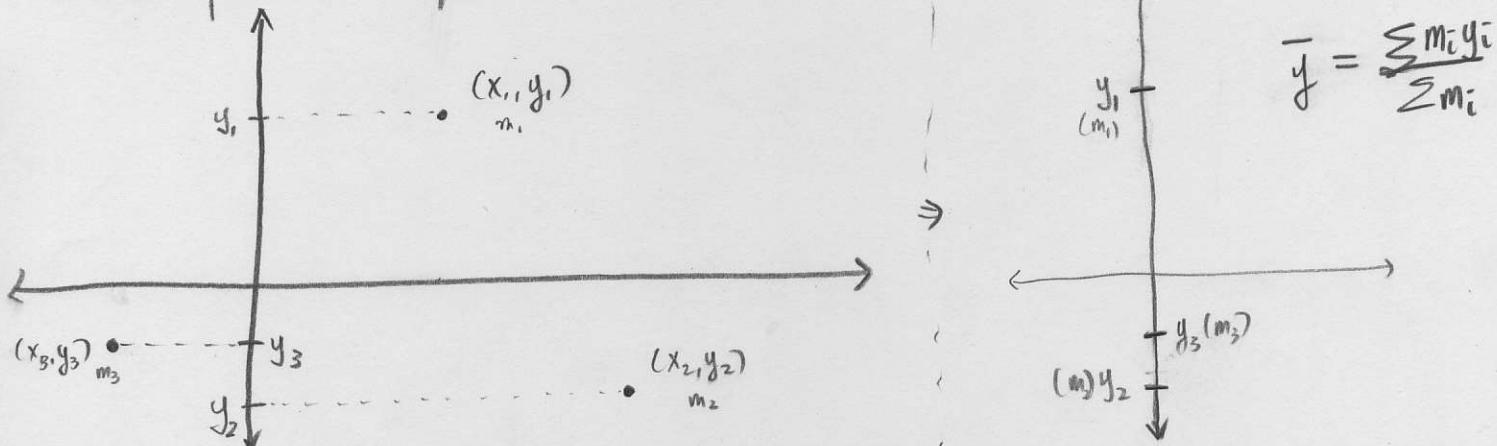
First Key Idea: To find the center of mass of point masses in a plane or a two-dimensional object with density (constant)  $\delta$ , you can find the center of mass for each coordinate individually - as though the masses were in a line rather than over a plane!

Example:

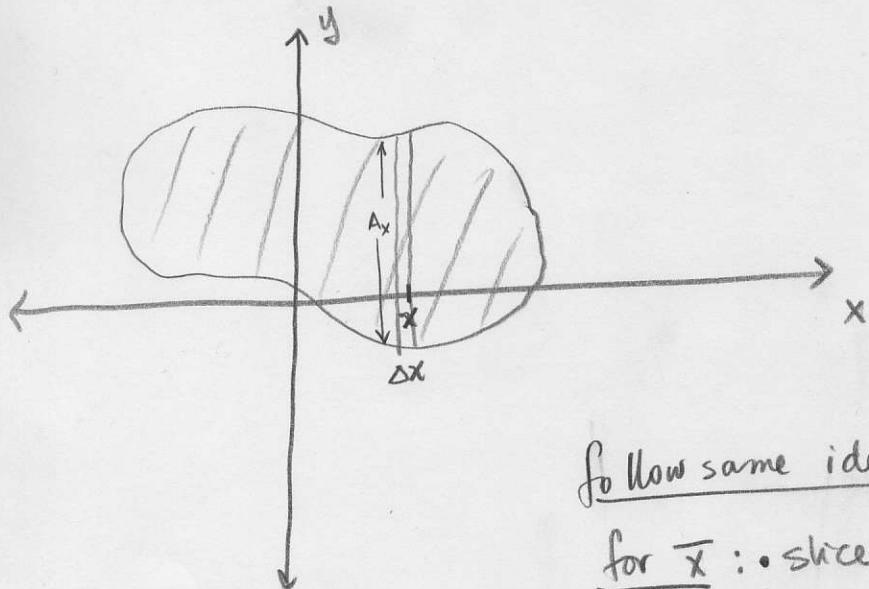
(Reduce to linear case in each component)



and for  $\bar{y}$  - ignore the  $x$ -component and compute as before:



So this is how it's done for discrete point masses in a plane. How about if I have a 2-D object with constant density  $\delta$ ?



Follow same ideas:

for  $\bar{x}$ : slice at values of  $x$  (i.e. vertically)

- the mass of that slice is

$$\text{mass} = \text{area} \times \text{density} = (A_x(x) \cdot \Delta x) \cdot \delta$$

where  $A_x(x) = \text{height of slice at } x$ .

→ moment for that slice is  $\underline{x} \cdot A_x(x) \Delta x \cdot \delta$

$$\text{so } \bar{x} \approx \frac{\sum x \cdot A_x(x) \Delta x \delta}{\sum A_x(x) \Delta x \delta} \Rightarrow \bar{x} = \frac{\int \delta x A_x(x) dx}{\int \delta A_x(x) dx}$$

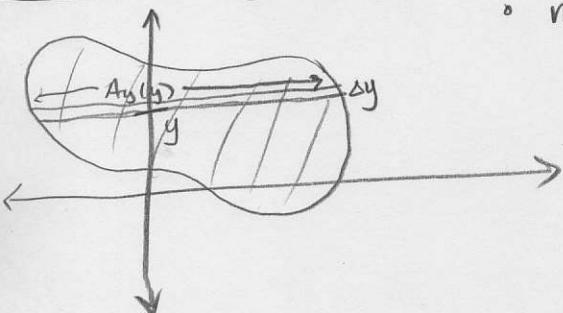
[Notice this is like reducing to the 1-D case by putting all of the mass at a fixed value of  $x$  (regardless of  $y$ -coord) as a point mass on the  $x$ -axis at location of the slice!]

Similarly for  $\bar{y}$ : slice at a value of  $y$  (horizontally)

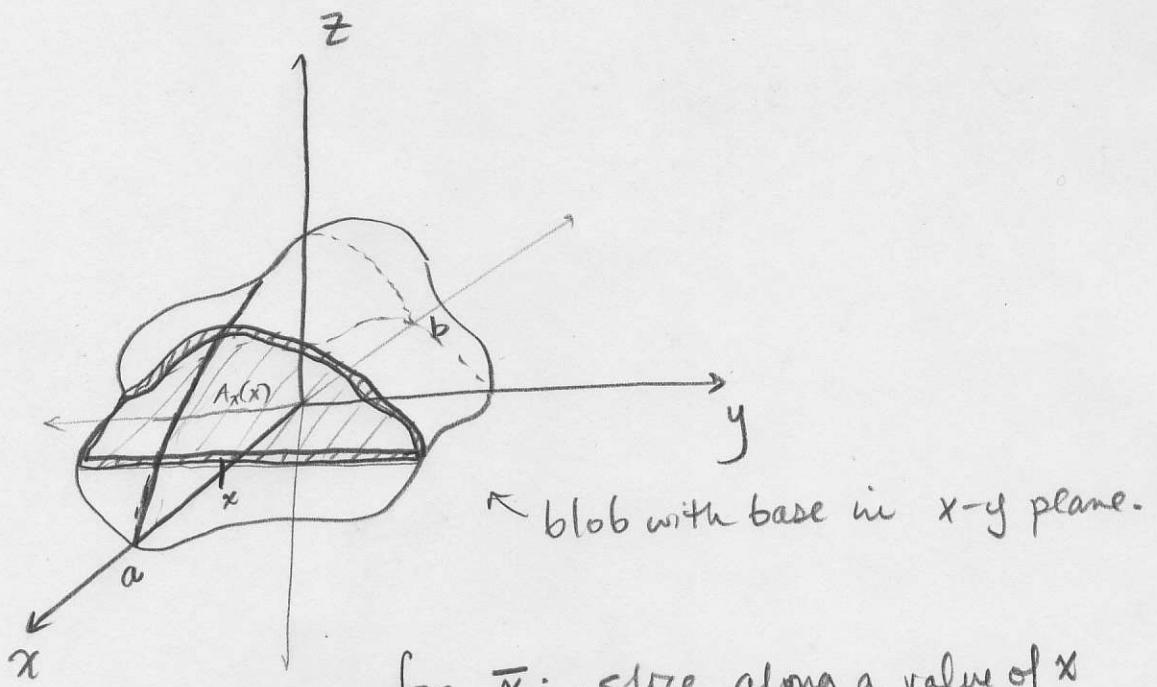
- mass of slice =  $\underline{\delta} \cdot A_y(y) \Delta y$

- moment of slice =  $y \cdot \delta A_y(y) \Delta y$

$$\bar{y} = \frac{\int \delta y A_y(y) dy}{\int \delta A_y(y) dy}$$



### 3D:



for  $\bar{x}$ : slice along a value of  $x$

- If the density is constant =  $\delta$ ,
- mass of slice  $\cong \underbrace{A_x(x) \Delta x}_{\text{volume}} \cdot \underbrace{\delta}_{\text{density}}$

where  $A_x(x)$  = surface area of slice at  $x$ !

$$\Rightarrow \bar{x} = \frac{\int_a^b \delta x \cdot A_x(x) dx}{\int_a^b \delta A_x(x) dx}$$

moment of slice  $\cong x \cdot A_x(x) \Delta x \cdot \delta$

(similarly:  $\bar{y} = \frac{\int \delta y A_y(y) dy}{\int \delta A_y(y) dy}$ ,  $\bar{z} = \frac{\int \delta z A_z(z) dz}{\int \delta A_z(z) dz}$ )

Again, this is like concentrating all of the mass in a slice at  $x$  into a point mass at  $x$  on the  $x$ -axis - ignoring other coordinates - so we essentially reduce to the 1D case again.