

**Labwork Set # 1 – Math 371 – Fall 2009 Due date: 9/8/2009**

1. Write the following “.m” function files:

- (a) [5 points] A function that takes in an arbitrary vector and a norm type (either 1,2,or inf), and returns the norm of the vector (using the type of norm specified in the input).
- (b) [5 points] A function that takes in an arbitrary matrix and a norm type (again, either 1,2,or inf), and returns the norm of the matrix.
- (c) [3 points] A function that takes in an arbitrary **square, invertible** matrix and a norm type, and uses part (b) to return the condition number of the matrix. Take one well-conditioned matrix and one ill-conditioned matrix and compare the values you get from your condition number function with the built-in value from the MATLAB function `cond(A,p)`.

Note: do not use built-in MATLAB functions that calculate the norms or condition number for you!

2. Note: this problem is connected to problems 2 and 3 of the written homework. Define the matrices  $A$  and  $B$  by:

$$A = \begin{bmatrix} 0.03 & 58.9 \\ 5.31 & -6.1 \end{bmatrix}$$

$$B = \begin{bmatrix} 0.780 & 0.564 \\ 0.913 & 0.659 \end{bmatrix}$$

- (a) [3 points] Use MATLAB (just so that the values are as close to the true values as possible) to obtain precisely the reduced forms of  $A$  and  $B$  that result from Gaussian elimination. Store these in MATLAB as  $rA$  and  $rB$ . From the written homework, enter the approximate reduced forms that you obtained using 3 digit arithmetic. Store these in MATLAB as  $cA$  and  $cB$ . (these stand for real A (rA) and computed A (cA))
- (b) [2 points] Compute the matrices  $\delta A = rA - cA$  and  $\delta B = rB - cB$ . Store these as  $dA$  and  $dB$  in MATLAB.
- (c) [2 points] Use the backslash operator to find the true solutions to  $A\vec{x} = \vec{b}$ , where  $\vec{b} = \langle 59.2, 47.0 \rangle$ , and to  $B\vec{x} = \vec{c}$  where  $\vec{c} = \langle .218, .254 \rangle$ .
- (d) [2 points] Compute the condition number of each matrix.
- (e) [3 points] Compute  $\frac{\|\delta\vec{x}\|}{\|\vec{x}\|}$ ,  $\frac{\|\delta\vec{b}\|}{\|\vec{b}\|}$ ,  $\frac{\|\delta A\|}{\|A\|}$ , and the corresponding values for the relative errors for  $B\vec{x} = \vec{c}$  using the functions you developed in number 1. Check to see that the inequality

$$\frac{\|\delta\vec{x}\|}{\|\vec{x}\|} \leq \kappa(A) \left( \frac{\|\delta A\|}{\|A\|} + \frac{\|\delta\vec{b}\|}{\|\vec{b}\|} \right)$$

from lecture is satisfied.

3. [5 points] Write a function that takes in an arbitrary upper triangular matrix  $U$  (so it is also square) and a vector  $\vec{b}$  and returns the solution to  $U\vec{x} = \vec{b}$  obtained by **back-substitution**.

(in other words, the solution is obtained in the same way we have been getting the final solution to a system in class – from the upper triangular matrix that is the end product of Gaussian elimination.. the last term  $x_n$  is easy to find, and then you use it in the second to last equation for  $x_{n-1}$ , and then use those two to find  $x_{n-2}$  etc.)

Be sure to check that it performs correctly by comparing to the solution found by MATLAB's backslash operator.